

A Linear Algebra package for REDUCE

Matt Rebbeck
Konrad-Zuse-Zentrum für Informationstechnik Berlin

July 1994

1 Introduction

This package provides a selection of functions that are useful in the world of linear algebra. These functions are described alphabetically in section 3 of this document and are labelled 3.1 to 3.51. They can be classified into four sections(n.b: the numbers after the dots signify the function label in section 3).

Contributions to this package have been made by Walter Tietze (ZIB).

1.1 Basic matrix handling

add_columns	...	3.1	add_rows	...	3.2
add_to_columns	...	3.3	add_to_rows	...	3.4
augment_columns	...	3.5	char_poly	...	3.9
column_dim	...	3.12	copy_into	...	3.14
diagonal	...	3.15	extend	...	3.16
find_companion	...	3.17	get_columns	...	3.18
get_rows	...	3.19	hermitian_tp	...	3.21
matrix_augment	...	3.28	matrix_stack	...	3.30
minor	...	3.31	mult_columns	...	3.32
mult_rows	...	3.33	pivot	...	3.34
remove_columns	...	3.37	remove_rows	...	3.38
row_dim	...	3.39	rows_pivot	...	3.40
stack_rows	...	3.43	sub_matrix	...	3.44
swap_columns	...	3.46	swap_entries	...	3.47
swap_rows	...	3.48			

1.2 Constructors

Functions that create matrices.

band_matrix	...	3. 6	block_matrix	...	3. 7
char_matrix	...	3. 8	coeff_matrix	...	3. 11
companion	...	3. 13	hessian	...	3. 22
hilbert	...	3. 23	jacobian	...	3. 24
jordan_block	...	3. 25	make_identity	...	3. 27
random_matrix	...	3. 36	toeplitz	...	3. 50
Vandermonde	...	3. 51	Kronecker_Product	...	3. 52

1.3 High level algorithms

char_poly	...	3.9	cholesky	...	3.10
gram_schmidt	...	3.20	lu_decom	...	3.26
pseudo_inverse	...	3.35	simplex	...	3.41
svd	...	3.45	triang_adjoint	...	3.51

There is a separate NORMFORM[1] package for computing the following matrix normal forms in REDUCE.

smithex, smithex.int, frobenius, ratjordan, jordansymbolic, jordan.

1.4 Predicates

matrixp ... 3.29 squarep ... 3.42
 symmetricp ... 3.49

Note on examples:

In the examples the matrix \mathcal{A} will be

$$\mathcal{A} = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$

Notation

Throughout \mathcal{I} is used to indicate the identity matrix and \mathcal{A}^T to indicate the transpose of the matrix \mathcal{A} .

2 Getting started

If you have not used matrices within REDUCE before then the following may be helpful.

Creating matrices

Initialisation of matrices takes the following syntax:

```
mat1 := mat((a,b,c),(d,e,f),(g,h,i));
```

will produce

$$\mathit{mat1} := \begin{pmatrix} a & b & c \\ d & e & f \\ g & h & i \end{pmatrix}$$

Getting at the entries

The (i,j)'th entry can be accessed by:

```
mat1(i,j);
```

Loading the linear_algebra package

The package is loaded by:

```
load_package linalg;
```

3 What's available

3.1 add_columns, add_rows

```
add_columns(A,c1,c2,expr);
```

\mathcal{A} :- a matrix.

$c1,c2$:- positive integers.

expr :- a scalar expression.

Synopsis:

`add_columns` replaces column $c2$ of \mathcal{A} by $\mathit{expr} * \mathit{column}(\mathcal{A},c1) + \mathit{column}(\mathcal{A},c2)$.

`add_rows` performs the equivalent task on the rows of \mathcal{A} .

Examples:

$$\mathit{add_columns}(\mathcal{A},1,2,x) = \begin{pmatrix} 1 & x+2 & 3 \\ 4 & 4*x+5 & 6 \\ 7 & 7*x+8 & 9 \end{pmatrix}$$

$$\text{add_rows}(\mathcal{A}, 2, 3, 5) = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 27 & 33 & 39 \end{pmatrix}$$

Related functions:

`add_to_columns`, `add_to_rows`, `mult_columns`, `mult_rows`.

3.2 add_rows

see: `add_columns`.

3.3 add_to_columns, add_to_rows

`add_to_columns`(\mathcal{A} , `column_list`, `expr`);

\mathcal{A} :- a matrix.

`column_list` :- a positive integer or a list of positive integers.

`expr` :- a scalar expression.

Synopsis:

`add_to_columns` adds `expr` to each column specified in `column_list` of \mathcal{A} .

`add_to_rows` performs the equivalent task on the rows of \mathcal{A} .

Examples:

$$\text{add_to_columns}(\mathcal{A}, \{1, 2\}, 10) = \begin{pmatrix} 11 & 12 & 3 \\ 14 & 15 & 6 \\ 17 & 18 & 9 \end{pmatrix}$$

$$\text{add_to_rows}(\mathcal{A}, 2, -x) = \begin{pmatrix} 1 & 2 & 3 \\ -x+4 & -x+5 & -x+6 \\ 7 & 8 & 9 \end{pmatrix}$$

Related functions:

`add_columns`, `add_rows`, `mult_rows`, `mult_columns`.

3.4 add_to_rows

see: `add_to_columns`.

3.5 `augment_columns`, `stack_rows`

```
augment_columns( $\mathcal{A}$ , column_list);
```

\mathcal{A} :- a matrix.

column_list :- either a positive integer or a list of positive integers.

Synopsis:

`augment_columns` gets hold of the columns of \mathcal{A} specified in `column_list` and sticks them together.

`stack_rows` performs the same task on rows of \mathcal{A} .

Examples:

$$\text{augment_columns}(\mathcal{A}, \{1, 2\}) = \begin{pmatrix} 1 & 2 \\ 4 & 5 \\ 7 & 8 \end{pmatrix}$$

$$\text{stack_rows}(\mathcal{A}, \{1, 3\}) = \begin{pmatrix} 1 & 2 & 3 \\ 7 & 8 & 9 \end{pmatrix}$$

Related functions:

`get_columns`, `get_rows`, `sub_matrix`.

3.6 `band_matrix`

```
band_matrix(expr_list, square_size);
```

`expr_list` :- either a single scalar expression or a list of an odd number of scalar expressions.

`square_size` :- a positive integer.

Synopsis:

`band_matrix` creates a square matrix of dimension `square_size`. The diagonal consists of the middle `expr` of the `expr_list`. The `exprs` to the left of this fill the required number of sub-diagonals and the `exprs` to the right the super-diagonals.

Examples:

$$\text{band_matrix}(\{x, y, z\}, 6) = \begin{pmatrix} y & z & 0 & 0 & 0 & 0 \\ x & y & z & 0 & 0 & 0 \\ 0 & x & y & z & 0 & 0 \\ 0 & 0 & x & y & z & 0 \\ 0 & 0 & 0 & x & y & z \\ 0 & 0 & 0 & 0 & x & y \end{pmatrix}$$

Related functions:

`diagonal`.

3.7 block_matrix

`block_matrix(r, c, matrix_list);`

`r, c` :- positive integers.

`matrix_list` :- a list of matrices.

Synopsis:

`block_matrix` creates a matrix that consists of `r` by `c` matrices filled from the `matrix_list` row wise.

Examples:

$$\mathcal{B} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad \mathcal{C} = \begin{pmatrix} 5 \\ 5 \end{pmatrix}, \quad \mathcal{D} = \begin{pmatrix} 22 & 33 \\ 44 & 55 \end{pmatrix}$$

$$\text{block_matrix}(2, 3, \{\mathcal{B}, \mathcal{C}, \mathcal{D}, \mathcal{D}, \mathcal{C}, \mathcal{B}\}) = \begin{pmatrix} 1 & 0 & 5 & 22 & 33 \\ 0 & 1 & 5 & 44 & 55 \\ 22 & 33 & 5 & 1 & 0 \\ 44 & 55 & 5 & 0 & 1 \end{pmatrix}$$

3.8 char_matrix

`char_matrix(A, λ);`

`A` :- a square matrix.

`λ` :- a symbol or algebraic expression.

Synopsis:

`char_matrix` creates the characteristic matrix \mathcal{C} of \mathcal{A} .

This is $C = \lambda * I - A$.

Examples:

$$\text{char_matrix}(A, x) = \begin{pmatrix} x-1 & -2 & -3 \\ -4 & x-5 & -6 \\ -7 & -8 & x-9 \end{pmatrix}$$

Related functions:

`char_poly`.

3.9 char_poly

`char_poly(A, λ);`

A :- a square matrix.

λ :- a symbol or algebraic expression.

Synopsis:

`char_poly` finds the characteristic polynomial of A .

This is the determinant of $\lambda * I - A$.

Examples:

$$\text{char_poly}(A, x) = x^3 - 15 * x^2 - 18 * x$$

Related functions:

`char_matrix`.

3.10 cholesky

`cholesky(A);`

A :- a positive definite matrix containing numeric entries.

Synopsis:

`cholesky` computes the cholesky decomposition of A .

It returns $\{\mathcal{L}, \mathcal{U}\}$ where \mathcal{L} is a lower matrix, \mathcal{U} is an upper matrix, $A = \mathcal{L}\mathcal{U}$, and $\mathcal{U} = \mathcal{L}^T$.

Examples:

$$\mathcal{F} = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 3 & 1 \\ 0 & 1 & 1 \end{pmatrix}$$

$$\text{cholesky}(\mathcal{F}) = \left\{ \begin{pmatrix} 1 & 0 & 0 \\ 1 & \sqrt{2} & 0 \\ 0 & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}, \begin{pmatrix} 1 & 1 & 0 \\ 0 & \sqrt{2} & \frac{1}{\sqrt{2}} \\ 0 & 0 & \frac{1}{\sqrt{2}} \end{pmatrix} \right\}$$

Related functions:

`lu.decom.`

3.11 coeff_matrix

`coeff_matrix({lin_eqn1, lin_eqn2, ..., lin_eqnn}); *`

`lin_eqn1, lin_eqn2, ..., lin_eqnn` :- linear equations. Can be of the form *equation = number* or just *equation*.

Synopsis:

`coeff_matrix` creates the coefficient matrix \mathcal{C} of the linear equations.

It returns $\{\mathcal{C}, \mathcal{X}, \mathcal{B}\}$ such that $\mathcal{C}\mathcal{X} = \mathcal{B}$.

Examples:

`coeff_matrix({x + y + 4 * z = 10, y + x - z = 20, x + y + 4}) =`

$$\left\{ \begin{pmatrix} 4 & 1 & 1 \\ -1 & 1 & 1 \\ 0 & 1 & 1 \end{pmatrix}, \begin{pmatrix} z \\ y \\ x \end{pmatrix}, \begin{pmatrix} 10 \\ 20 \\ -4 \end{pmatrix} \right\}$$

3.12 column_dim, row_dim

`column_dim(A);`

`A` :- a matrix.

Synopsis:

`column_dim` finds the column dimension of \mathcal{A} .

*If you're feeling lazy then the `{}`'s can be omitted.

`row_dim` finds the row dimension of \mathcal{A} .

Examples:

`column_dim(A) = 3`

3.13 companion

`companion(poly,x);`

`poly` :- a monic univariate polynomial in x .

`x` :- the variable.

Synopsis:

`companion` creates the companion matrix \mathcal{C} of `poly`.

This is the square matrix of dimension n , where n is the degree of `poly` w.r.t. x .

The entries of \mathcal{C} are: $\mathcal{C}(i,n) = -\text{coeffn}(\text{poly},x,i-1)$ for $i = 1 \dots n$, $\mathcal{C}(i,i-1) = 1$ for $i = 2 \dots n$ and the rest are 0.

Examples:

$$\text{companion}(x^4 + 17 * x^3 - 9 * x^2 + 11, x) = \begin{pmatrix} 0 & 0 & 0 & -11 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 9 \\ 0 & 0 & 1 & -17 \end{pmatrix}$$

Related functions:

`find_companion`.

3.14 copy_into

`copy_into(A,B,r,c);`

`A,B` :- matrices.

`r,c` :- positive integers.

Synopsis:

`copy_into` copies matrix \mathcal{A} into \mathcal{B} with $\mathcal{A}(1,1)$ at $\mathcal{B}(r,c)$.

Examples:

$$\mathcal{G} = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\text{copy_into}(\mathcal{A}, \mathcal{G}, 1, 2) = \begin{pmatrix} 0 & 1 & 2 & 3 \\ 0 & 4 & 5 & 6 \\ 0 & 7 & 8 & 9 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Related functions:

`augment_columns`, `extend`, `matrix_augment`, `matrix_stack`, `stack_rows`,
`sub_matrix`.

3.15 diagonal

`diagonal({mat1, mat2, ..., matn});`[†]

`mat1, mat2, ..., matn` :- each can be either a scalar expr or a square matrix.

Synopsis:

`diagonal` creates a matrix that contains the input on the diagonal.

Examples:

$$\mathcal{H} = \begin{pmatrix} 66 & 77 \\ 88 & 99 \end{pmatrix}$$

$$\text{diagonal}(\{\mathcal{A}, x, \mathcal{H}\}) = \begin{pmatrix} 1 & 2 & 3 & 0 & 0 & 0 \\ 4 & 5 & 6 & 0 & 0 & 0 \\ 7 & 8 & 9 & 0 & 0 & 0 \\ 0 & 0 & 0 & x & 0 & 0 \\ 0 & 0 & 0 & 0 & 66 & 77 \\ 0 & 0 & 0 & 0 & 88 & 99 \end{pmatrix}$$

Related functions:

`jordan_block`.

[†]If you're feeling lazy then the `{}`'s can be omitted.

3.16 extend

```
extend( $\mathcal{A}$ , r, c, expr);
```

\mathcal{A} :- a matrix.

r,c :- positive integers.

expr :- algebraic expression or symbol.

Synopsis:

`extend` returns a copy of \mathcal{A} that has been extended by r rows and c columns. The new entries are made equal to `expr`.

Examples:

$$\text{extend}(\mathcal{A}, 1, 2, x) = \begin{pmatrix} 1 & 2 & 3 & x & x \\ 4 & 5 & 6 & x & x \\ 7 & 8 & 9 & x & x \\ x & x & x & x & x \end{pmatrix}$$

Related functions:

`copy_into`, `matrix_augment`, `matrix_stack`, `remove_columns`,
`remove_rows`.

3.17 find_companion

```
find_companion( $\mathcal{A}$ , x);
```

\mathcal{A} :- a matrix.

x :- the variable.

Synopsis:

Given a companion matrix, `find_companion` finds the polynomial from which it was made.

Examples:

$$\mathcal{C} = \begin{pmatrix} 0 & 0 & 0 & -11 \\ 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 9 \\ 0 & 0 & 1 & -17 \end{pmatrix}$$

$$\text{find_companion}(\mathcal{C}, x) = x^4 + 17 * x^3 - 9 * x^2 + 11$$

Related functions:

companion.

3.18 get_columns, get_rows

`get_columns(A, column_list);`

\mathcal{A} :- a matrix.

c :- either a positive integer or a list of positive integers.

Synopsis:

`get_columns` removes the columns of \mathcal{A} specified in `column_list` and returns them as a list of column matrices.

`get_rows` performs the same task on the rows of \mathcal{A} .

Examples:

$$\text{get_columns}(\mathcal{A}, \{1, 3\}) = \left\{ \left(\begin{array}{c} 1 \\ 4 \\ 7 \end{array} \right), \left(\begin{array}{c} 3 \\ 6 \\ 9 \end{array} \right) \right\}$$

$$\text{get_rows}(\mathcal{A}, 2) = \left\{ (4 \ 5 \ 6) \right\}$$

Related functions:

augment_columns, stack_rows, sub_matrix.

3.19 get_rows

see: `get_columns`.

3.20 gram_schmidt

`gram_schmidt({vec1, vec2, ..., vecn});‡`

[‡]If you're feeling lazy then the `{}`'s can be omitted.

$\text{vec}_1, \text{vec}_2, \dots, \text{vec}_n$:- linearly independent vectors. Each vector must be written as a list, eg: {1,0,0}.

Synopsis:

`gram_schmidt` performs the `gram_schmidt` orthonormalisation on the input vectors.

It returns a list of orthogonal normalised vectors.

Examples:

`gram_schmidt`({{1,0,0},{1,1,0},{1,1,1}}) = {{1,0,0},{0,1,0},{0,0,1}}

`gram_schmidt`({{1,2},{3,4}}) = {{ $\frac{1}{\sqrt{5}}, \frac{2}{\sqrt{5}}$ }, { $\frac{2*\sqrt{5}}{5}, \frac{-\sqrt{5}}{5}$ }}

3.21 hermitian_tp

`hermitian_tp`(\mathcal{A});

\mathcal{A} :- a matrix.

Synopsis:

`hermitian_tp` computes the hermitian transpose of \mathcal{A} .

This is a matrix in which the (i,j)'th entry is the conjugate of the (j,i)'th entry of \mathcal{A} .

Examples:

$$\mathcal{J} = \begin{pmatrix} i+1 & i+2 & i+3 \\ 4 & 5 & 2 \\ 1 & i & 0 \end{pmatrix}$$

$$\text{hermitian_tp}(\mathcal{J}) = \begin{pmatrix} -i+1 & 4 & 1 \\ -i+2 & 5 & -i \\ -i+3 & 2 & 0 \end{pmatrix}$$

Related functions:

`tp`[§].

[§]standard reduce call for the transpose of a matrix - see REDUCE User's Manual[2].

3.22 hessian

`hessian(expr,variable_list);`

`expr` :- a scalar expression.

`variable_list` :- either a single variable or a list of variables.

Synopsis:

`hessian` computes the hessian matrix of `expr` w.r.t. the variables in `variable_list`.

This is an n by n matrix where n is the number of variables and the (i,j) 'th entry is `df(expr,variable_list(i),variable_list(j))`.

Examples:

$$\text{hessian}(x * y * z + x^2, \{w, x, y, z\}) = \begin{pmatrix} 0 & 0 & 0 & 0 \\ 0 & 2 & z & y \\ 0 & z & 0 & x \\ 0 & y & x & 0 \end{pmatrix}$$

Related functions:

`df`[¶].

3.23 hilbert

`hilbert(square_size,expr);`

`square_size` :- a positive integer.

`expr` :- an algebraic expression.

Synopsis:

`hilbert` computes the square hilbert matrix of dimension `square_size`.

This is the symmetric matrix in which the (i,j) 'th entry is $1/(i+j-\text{expr})$.

Examples:

$$\text{hilbert}(3, y + x) = \begin{pmatrix} \frac{-1}{x+y-2} & \frac{-1}{x+y-3} & \frac{-1}{x+y-4} \\ \frac{-1}{x+y-3} & \frac{-1}{x+y-4} & \frac{-1}{x+y-5} \\ \frac{-1}{x+y-4} & \frac{-1}{x+y-5} & \frac{-1}{x+y-6} \end{pmatrix}$$

[¶]standard reduce call for differentiation - see REDUCE User's Manual[2]

3.24 jacobian

`jacobian(expr_list, variable_list);`

`expr_list` :- either a single algebraic expression or a list of algebraic expressions.

`variable_list` :- either a single variable or a list of variables.

Synopsis:

`jacobian` computes the jacobian matrix of `expr_list` w.r.t. `variable_list`.

This is a matrix whose (i,j)'th entry is $df(\text{expr_list}(i), \text{variable_list}(j))$.

The matrix is n by m where n is the number of variables and m the number of expressions.

Examples:

`jacobian({x4, x * y2, x * y * z3}, {w, x, y, z}) =`

$$\begin{pmatrix} 0 & 4 * x^3 & 0 & 0 \\ 0 & y^2 & 2 * x * y & 0 \\ 0 & y * z^3 & x * z^3 & 3 * x * y * z^2 \end{pmatrix}$$

Related functions:

`hessian`, `df`^{||}.

3.25 jordan_block

`jordan_block(expr, square_size);`

`expr` :- an algebraic expression or symbol.

`square_size` :- a positive integer.

Synopsis:

`jordan_block` computes the square jordan block matrix \mathcal{J} of dimension `square_size`.

The entries of \mathcal{J} are: $\mathcal{J}(i,i) = \text{expr}$ for $i=1 \dots n$, $\mathcal{J}(i,i+1) = 1$ for $i=1 \dots n-1$, and all other entries are 0.

^{||}standard reduce call for differentiation - see REDUCE User's Manual[2].

Examples:

$$\text{jordan_block}(x,5) = \begin{pmatrix} x & 1 & 0 & 0 & 0 \\ 0 & x & 1 & 0 & 0 \\ 0 & 0 & x & 1 & 0 \\ 0 & 0 & 0 & x & 1 \\ 0 & 0 & 0 & 0 & x \end{pmatrix}$$

Related functions:

`diagonal`, `companion`.

3.26 lu_decom

`lu_decom(A)`;

\mathcal{A} :- a matrix containing either numeric entries or imaginary entries with numeric coefficients.

Synopsis:

`lu_decom` performs LU decomposition on \mathcal{A} , ie: it returns $\{\mathcal{L}, \mathcal{U}\}$ where \mathcal{L} is a lower diagonal matrix, \mathcal{U} an upper diagonal matrix and $\mathcal{A} = \mathcal{L}\mathcal{U}$.

caution:

The algorithm used can swap the rows of \mathcal{A} during the calculation. This means that $\mathcal{L}\mathcal{U}$ does not equal \mathcal{A} but a row equivalent of it. Due to this, `lu_decom` returns $\{\mathcal{L}, \mathcal{U}, \text{vec}\}$. The call `convert(A,vec)` will return the matrix that has been decomposed, ie: $\mathcal{L}\mathcal{U} = \text{convert}(\mathcal{A}, \text{vec})$.

Examples:

$$\mathcal{K} = \begin{pmatrix} 1 & 3 & 5 \\ -4 & 3 & 7 \\ 8 & 6 & 4 \end{pmatrix}$$

$$\text{lu} := \text{lu_decom}(\mathcal{K}) = \left\{ \begin{pmatrix} 8 & 0 & 0 \\ -4 & 6 & 0 \\ 1 & 2.25 & 1.1251 \end{pmatrix}, \begin{pmatrix} 1 & 0.75 & 0.5 \\ 0 & 1 & 1.5 \\ 0 & 0 & 1 \end{pmatrix}, [3 \ 2 \ 3] \right\}$$

$$\text{first lu} * \text{second lu} = \begin{pmatrix} 8 & 6 & 4 \\ -4 & 3 & 7 \\ 1 & 3 & 5 \end{pmatrix}$$

$$\text{convert}(\mathcal{K}, \text{third lu}) = \begin{pmatrix} 8 & 6 & 4 \\ -4 & 3 & 7 \\ 1 & 3 & 5 \end{pmatrix}$$

$$\mathcal{P} = \begin{pmatrix} i+1 & i+2 & i+3 \\ 4 & 5 & 2 \\ 1 & i & 0 \end{pmatrix}$$

$$\text{lu} := \text{lu_decom}(\mathcal{P}) = \left\{ \begin{pmatrix} 1 & 0 & 0 \\ 4 & -4*i+5 & 0 \\ i+1 & 3 & 0.41463*i+2.26829 \end{pmatrix}, \begin{pmatrix} 1 & i & 0 \\ 0 & 1 & 0.19512*i+0.24390 \\ 0 & 0 & 1 \end{pmatrix}, [3\ 2\ 3] \right\}$$

$$\text{first lu} * \text{second lu} = \begin{pmatrix} 1 & i & 0 \\ 4 & 5 & 2 \\ i+1 & i+2 & i+3 \end{pmatrix}$$

$$\text{convert}(\mathcal{P}, \text{third lu}) = \begin{pmatrix} 1 & i & 0 \\ 4 & 5 & 2 \\ i+1 & i+2 & i+3 \end{pmatrix}$$

Related functions:

cholesky.

3.27 make_identity

make_identity(square_size);

square_size :- a positive integer.

Synopsis:

make_identity creates the identity matrix of dimension square_size.

Examples:

$$\text{make_identity}(4) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Related functions:

`diagonal`.

3.28 `matrix_augment`, `matrix_stack`

`matrix_augment({mat1, mat2, ..., matn});**`

`mat1, mat2, ..., matn` :- matrices.

Synopsis:

`matrix_augment` sticks the matrices in `matrix_list` together horizontally.

`matrix_stack` sticks the matrices in `matrix_list` together vertically.

Examples:

$$\text{matrix_augment}(\{\mathcal{A}, \mathcal{A}\}) = \begin{pmatrix} 1 & 2 & 3 & 1 & 2 & 3 \\ 4 & 4 & 6 & 4 & 5 & 6 \\ 7 & 8 & 9 & 7 & 8 & 9 \end{pmatrix}$$

$$\text{matrix_stack}(\{\mathcal{A}, \mathcal{A}\}) = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \\ 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$

Related functions:

`augment_columns`, `stack_rows`, `sub_matrix`.

3.29 `matrixp`

`matrixp(test_input);`

**If you're feeling lazy then the `{}`'s can be omitted.

`test_input` :- anything you like.

Synopsis:

`matrixp` is a boolean function that returns `t` if the input is a matrix and `nil` otherwise.

Examples:

`matrixp(A) = t`

`matrixp(doodlesackbanana) = nil`

Related functions:

`squarep`, `symmetricp`.

3.30 `matrix_stack`

see: `matrix_augment`.

3.31 `minor`

`minor(A, r, c);`

`A` :- a matrix.

`r, c` :- positive integers.

Synopsis:

`minor` computes the (r,c) 'th minor of \mathcal{A} .

This is created by removing the r 'th row and the c 'th column from \mathcal{A} .

Examples:

$$\text{minor}(\mathcal{A}, 1, 3) = \begin{pmatrix} 4 & 5 \\ 7 & 8 \end{pmatrix}$$

Related functions:

`remove_columns`, `remove_rows`.

3.32 `mult_columns`, `mult_rows`

`mult_columns(A, column_list, expr);`

\mathcal{A} :- a matrix.
 column_list :- a positive integer or a list of positive integers.
 expr :- an algebraic expression.

Synopsis:

`mult_columns` returns a copy of \mathcal{A} in which the columns specified in `column_list` have been multiplied by `expr`.

`mult_rows` performs the same task on the rows of \mathcal{A} .

Examples:

$$\text{mult_columns}(\mathcal{A}, \{1, 3\}, x) = \begin{pmatrix} x & 2 & 3 * x \\ 4 * x & 5 & 6 * x \\ 7 * x & 8 & 9 * x \end{pmatrix}$$

$$\text{mult_rows}(\mathcal{A}, 2, 10) = \begin{pmatrix} 1 & 2 & 3 \\ 40 & 50 & 60 \\ 7 & 8 & 9 \end{pmatrix}$$

Related functions:

`add_to_columns`, `add_to_rows`.

3.33 mult_rows

see: `mult_columns`.

3.34 pivot

`pivot`(\mathcal{A} , `r`, `c`);

\mathcal{A} :- a matrix.

`r`, `c` :- positive integers such that $\mathcal{A}(r,c) \neq 0$.

Synopsis:

`pivot` pivots \mathcal{A} about its (`r`,`c`)'th entry.

To do this, multiples of the `r`'th row are added to every other row in the matrix.

This means that the `c`'th column will be 0 except for the (`r`,`c`)'th entry.

Examples:

$$\text{pivot}(\mathcal{A}, 2, 3) = \begin{pmatrix} -1 & -0.5 & 0 \\ 4 & 5 & 6 \\ 1 & 0.5 & 0 \end{pmatrix}$$

Related functions:

`rows_pivot`.

3.35 pseudo_inverse

`pseudo_inverse(A)`;

\mathcal{A} :- a matrix.

Synopsis:

`pseudo_inverse`, also known as the Moore-Penrose inverse, computes the pseudo inverse of \mathcal{A} .

Given the singular value decomposition of \mathcal{A} , i.e: $\mathcal{A} = \mathcal{U} \Sigma \mathcal{V}^T$, then the pseudo inverse \mathcal{A}^{-1} is defined by $\mathcal{A}^{-1} = \mathcal{V}^T \Sigma^{-1} \mathcal{U}$.

Thus $\mathcal{A} * \text{pseudo_inverse}(\mathcal{A}) = \mathcal{I}$.

Examples:

$$\text{pseudo_inverse}(\mathcal{A}) = \begin{pmatrix} -0.2 & 0.1 \\ -0.05 & 0.05 \\ 0.1 & 0 \\ 0.25 & -0.05 \end{pmatrix}$$

Related functions:

`svd`.

3.36 random_matrix

`random_matrix(r,c,limit)`;

r, c, limit :- positive integers.

Synopsis:

`random_matrix` creates an r by c matrix with random entries in the range

–limit < entry < limit.

switches:

`imaginary` :- if on then matrix entries are $x+i*y$ where $-\text{limit} < x,y < \text{limit}$.

`not_negative` :- if on then $0 < \text{entry} < \text{limit}$. In the imaginary case we have $0 < x,y < \text{limit}$.

`only_integer` :- if on then each entry is an integer. In the imaginary case x and y are integers.

`symmetric` :- if on then the matrix is symmetric.

`upper_matrix` :- if on then the matrix is upper triangular.

`lower_matrix` :- if on then the matrix is lower triangular.

Examples:

$$\text{random_matrix}(3,3,10) = \begin{pmatrix} -4.729721 & 6.987047 & 7.521383 \\ -5.224177 & 5.797709 & -4.321952 \\ -9.418455 & -9.94318 & -0.730980 \end{pmatrix}$$

on `only_integer`, `not_negative`, `upper_matrix`, `imaginary`;

$$\text{random_matrix}(4,4,10) = \begin{pmatrix} 2*i+5 & 3*i+7 & 7*i+3 & 6 \\ 0 & 2*i+5 & 5*i+1 & 2*i+1 \\ 0 & 0 & 8 & i \\ 0 & 0 & 0 & 5*i+9 \end{pmatrix}$$

3.37 `remove_columns`, `remove_rows`

`remove_columns(A,column_list);`

\mathcal{A} :- a matrix.

`column_list` :- either a positive integer or a list of positive integers.

Synopsis:

`remove_columns` removes the columns specified in `column_list` from \mathcal{A} .

`remove_rows` performs the same task on the rows of \mathcal{A} .

Examples:

$$\text{remove_columns}(\mathcal{A}, 2) = \begin{pmatrix} 1 & 3 \\ 4 & 6 \\ 7 & 9 \end{pmatrix}$$

$$\text{remove_rows}(\mathcal{A}, \{1, 3\}) = \begin{pmatrix} 4 & 5 & 6 \end{pmatrix}$$

Related functions:

`minor`.

3.38 remove_rows

see: `remove_columns`.

3.39 row_dim

see: `column_dim`.

3.40 rows_pivot

`rows_pivot(A, r, c, {row_list});`

\mathcal{A} :- a matrix.

r, c :- positive integers such that $\mathcal{A}(r, c) \neq 0$.

`row_list` :- positive integer or a list of positive integers.

Synopsis:

`rows_pivot` performs the same task as `pivot` but applies the pivot only to the rows specified in `row_list`.

Examples:

$$\mathcal{N} = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \\ 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}$$

$$\text{rows_pivot}(\mathcal{N}, 2, 3, \{4, 5\}) = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \\ -0.75 & 0 & 0.75 \\ -0.375 & 0 & 0.375 \end{pmatrix}$$

Related functions:

`pivot`.

3.41 simplex

`simplex(max/min, objective function, {linear inequalities});`

`max/min` :- either max or min (signifying maximise and minimise).

`objective function` :- the function you are maximising or minimising.

`linear inequalities` :- the constraint inequalities. Each one must be of the form *sum of variables* (`<=`, `=`, `>=`) *number*.

Synopsis:

`simplex` applies the revised simplex algorithm to find the optimal (either maximum or minimum) value of the objective function under the linear inequality constraints.

It returns {optimal value, { values of variables at this optimal}}.

The algorithm implies that all the variables are non-negative.

Examples:

`simplex(max, x + y, {x >= 10, y >= 20, x + y <= 25});`

******* Error in simplex: Problem has no feasible solution.**

`simplex(max, 10x + 5y + 5.5z, {5x + 3z <= 200, x + 0.1y + 0.5z <= 12, 0.1x + 0.2y + 0.3z <= 9, 30x + 10y + 50z <= 1500});`

{525.0, {x = 40.0, y = 25.0, z = 0}}

3.42 squarep

```
squarep( $\mathcal{A}$ );
```

\mathcal{A} :- a matrix.

Synopsis:

`squarep` is a boolean function that returns `t` if the matrix is square and `nil` otherwise.

Examples:

$$\mathcal{L} = \begin{pmatrix} 1 & 3 & 5 \end{pmatrix}$$

```
squarep( $\mathcal{A}$ ) = t
```

```
squarep( $\mathcal{L}$ ) = nil
```

Related functions:

`matrixp`, `symmetricp`.

3.43 stack_rows

see: `augment_columns`.

3.44 sub_matrix

```
sub_matrix( $\mathcal{A}$ , row_list, column_list);
```

\mathcal{A} :- a matrix.

row_list, column_list :- either a positive integer or a list of positive integers.

Synopsis:

`sub_matrix` produces the matrix consisting of the intersection of the rows specified in `row_list` and the columns specified in `column_list`.

Examples:

$$\text{sub_matrix}(\mathcal{A}, \{1, 3\}, \{2, 3\}) = \begin{pmatrix} 2 & 3 \\ 8 & 9 \end{pmatrix}$$

Related functions:

`augment_columns`, `stack_rows`.

3.45 svd (singular value decomposition)

`svd(A)`;

A :- a matrix containing only numeric entries.

Synopsis:

`svd` computes the singular value decomposition of A .

It returns $\{U, \Sigma, V\}$ where $A = U \Sigma V^T$ and $\Sigma = \text{diag}(\sigma_1, \dots, \sigma_n)$. σ_i for $i = (1 \dots n)$ are the singular values of A .

n is the column dimension of A .

The singular values of A are the non-negative square roots of the eigenvalues of $A^T A$.

U and V are such that $UU^T = VV^T = V^T V = I_n$.

Examples:

$$Q = \begin{pmatrix} 1 & 3 \\ -4 & 3 \end{pmatrix}$$

$$\text{svd}(Q) = \left\{ \begin{pmatrix} 0.289784 & 0.957092 \\ -0.957092 & 0.289784 \end{pmatrix}, \begin{pmatrix} 5.149162 & 0 \\ 0 & 2.913094 \end{pmatrix}, \begin{pmatrix} -0.687215 & 0.726453 \\ -0.726453 & -0.687215 \end{pmatrix} \right\}$$

3.46 swap_columns, swap_rows

`swap_columns(A, c1, c2)`;

A :- a matrix.

`c1, c2` :- positive integers.

Synopsis:

`swap_columns` swaps column `c1` of A with column `c2`.

`swap_rows` performs the same task on 2 rows of \mathcal{A} .

Examples:

$$\text{swap_columns}(\mathcal{A}, 2, 3) = \begin{pmatrix} 1 & 3 & 2 \\ 4 & 6 & 5 \\ 7 & 9 & 8 \end{pmatrix}$$

Related functions:

`swap_entries`.

3.47 `swap_entries`

`swap_entries`(\mathcal{A} , { $r1$, $c1$ }, { $r2$, $c2$ });

\mathcal{A} :- a matrix.

$r1, c1, r2, c2$:- positive integers.

Synopsis:

`swap_entries` swaps $\mathcal{A}(r1, c1)$ with $\mathcal{A}(r2, c2)$.

Examples:

$$\text{swap_entries}(\mathcal{A}, \{1, 1\}, \{3, 3\}) = \begin{pmatrix} 9 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 1 \end{pmatrix}$$

Related functions:

`swap_columns`, `swap_rows`.

3.48 `swap_rows`

see: `swap_columns`.

3.49 `symmetricp`

`symmetricp`(\mathcal{A});

\mathcal{A} :- a matrix.

Synopsis:

`symmetricp` is a boolean function that returns `t` if the matrix is symmetric and `nil` otherwise.

Examples:

$$\mathcal{M} = \begin{pmatrix} 1 & 2 \\ 2 & 1 \end{pmatrix}$$

`symmetricp(A) = nil`

`symmetricp(M) = t`

Related functions:

`matrixp`, `squarep`.

3.50 `toeplitz`

`toeplitz({expr1, expr2, ..., exprn});` ^{††}

`expr1, expr2, ..., exprn` :- algebraic expressions.

Synopsis:

`toeplitz` creates the toeplitz matrix from the expression list.

This is a square symmetric matrix in which the first expression is placed on the diagonal and the *i*'th expression is placed on the (*i*-1)'th sub and super diagonals.

It has dimension *n* where *n* is the number of expressions.

Examples:

$$\text{toeplitz}(\{w, x, y, z\}) = \begin{pmatrix} w & x & y & z \\ x & w & x & y \\ y & x & w & x \\ z & y & x & w \end{pmatrix}$$

3.51 `triang_adjoint`

`triang_adjoint(A);`

^{††}If you're feeling lazy then the `{}`'s can be omitted.

\mathcal{A} :- a matrix.

Synopsis:

`triang_adjoint` computes the triangularizing adjoint \mathcal{F} of matrix \mathcal{A} due to the algorithm of Arne Storjohann. \mathcal{F} is lower triangular matrix and the resulting matrix \mathcal{T} of $\mathcal{F} * \mathcal{A} = \mathcal{T}$ is upper triangular with the property that the i -th entry in the diagonal of \mathcal{T} is the determinant of the principal i -th submatrix of the matrix \mathcal{A} .

Examples:

$$\text{triang_adjoint}(\mathcal{A}) = \begin{pmatrix} 1 & 0 & 0 \\ -4 & 1 & 0 \\ -3 & 6 & -3 \end{pmatrix}$$

$$\mathcal{F} * \mathcal{A} = \begin{pmatrix} 1 & 2 & 3 \\ 0 & -3 & -6 \\ 0 & 0 & 0 \end{pmatrix}$$

3.52 Vandermonde

`vandermonde`({`expr1`,`expr2`, ...,`exprn`}); ††

`expr1`,`expr2`, ...,`exprn` :- algebraic expressions.

Synopsis:

`Vandermonde` creates the Vandermonde matrix from the expression list.

This is the square matrix in which the (i,j)'th entry is `expr_list(i)` ^(j-1).

It has dimension n where n is the number of expressions.

Examples:

$$\text{vandermonde}(\{x, 2 * y, 3 * z\}) = \begin{pmatrix} 1 & x & x^2 \\ 1 & 2 * y & 4 * y^2 \\ 1 & 3 * z & 9 * z^2 \end{pmatrix}$$

3.53 kronecker_product

`kronecker_product`(`Mat1`, `Mat2`)

Mat_1, Mat_2 :- Matrices

Synopsis:

`kroncker_product` creates a matrix containing the Kronecker product (also called `direct product` or `tensor product`) of its arguments.

Examples:

```
a1 := mat((1,2), (3,4), (5,6))$
a2 := mat((1,1,1), (2,z,2), (3,3,3))$
kroncker_product(a1,a2);
```

$$\begin{pmatrix} 1 & 1 & 1 & 2 & 2 & 2 \\ 2 & z & 2 & 4 & 2*z & 4 \\ 3 & 3 & 3 & 6 & 6 & 6 \\ 3 & 3 & 3 & 4 & 4 & 4 \\ 6 & 3*z & 6 & 8 & 4*z & 8 \\ 9 & 9 & 9 & 12 & 12 & 12 \\ 5 & 5 & 5 & 6 & 6 & 6 \\ 10 & 5*z & 10 & 12 & 6*z & 12 \\ 15 & 15 & 15 & 18 & 18 & 18 \end{pmatrix}$$

4 Fast Linear Algebra

By turning the `fast_la` switch on, the speed of the following functions will be increased:

<code>add_columns</code>	<code>add_rows</code>	<code>augment_columns</code>	<code>column_dim</code>
<code>copy_into</code>	<code>make_identity</code>	<code>matrix_augment</code>	<code>matrix_stack</code>
<code>minor</code>	<code>mult_column</code>	<code>mult_row</code>	<code>pivot</code>
<code>remove_columns</code>	<code>remove_rows</code>	<code>rows_pivot</code>	<code>squarep</code>
<code>stack_rows</code>	<code>sub_matrix</code>	<code>swap_columns</code>	<code>swap_entries</code>
<code>swap_rows</code>	<code>symmetricp</code>		

The increase in speed will be insignificant unless you are making a significant number(i.e: thousands) of calls. When using this switch, error checking is minimised. This means that illegal input may give strange error messages. Beware.

5 Acknowledgments

Many of the ideas for this package came from the Maple[3] Linalg package [4].

The algorithms for `cholesky`, `lu_decom`, and `svd` are taken from the book Linear Algebra - J.H. Wilkinson & C. Reinsch[5].

The `gram_schmidt` code comes from Karin Gatermann's Symmetry package[6] for REDUCE.

References

- [1] Matt Rebeck: NORMFORM: A REDUCE package for the computation of various matrix normal forms. ZIB, Berlin. (1993)
- [2] Anthony C. Hearn: REDUCE User's Manual 3.6. RAND (1995)
- [3] Bruce W. Char... [et al.]: Maple (Computer Program). Springer-Verlag (1991)
- [4] Linalg - a linear algebra package for Maple[3].
- [5] J. H. Wilkinson & C. Reinsch: Linear Algebra (volume II). Springer-Verlag (1971)
- [6] Karin Gatermann: Symmetry: A REDUCE package for the computation of linear representations of groups. ZIB, Berlin. (1992)